

(see syllabus) (see syllabus) credit card (AMS131 23 Apr 19)

see document screening case study (continued) ①

answers notes 18 Apr 19

we know

$P(B) = 0.01$

$P(\ominus | G) = 0.97$

$P(\oplus | B) = 0.98$

we want $P(B | \oplus)$

only 2 possible truth states (B, G)

truth (unknown) system stays (data)

solution method 1: 2x2 table

method 2: Bayes's Theorem in odds form

earlier we showed that (likelihood ratio)

$$\frac{P(B | \oplus)}{P(\text{not } B | \oplus)} = \left[\frac{P(B)}{P(\text{not } B)} \right] \cdot \left[\frac{P(\oplus | B)}{P(\oplus | \text{not } B)} \right] \quad (*)$$

posterior odds in favor of B = (prior odds in favor of B) · (Bayes factor in favor of B)

excellent fact: we know all the probabilities on the right-hand side of \oplus

$$P(B) = 0.01$$

$$P(\text{not } B) = P(G) = 0.99$$

$$P(\oplus | B) = 0.98$$

$$P(\oplus | \text{not } B) =$$

$$1 - P(\ominus | B)$$

$$= 1 - P(\ominus | G)$$

$$= 1 - 0.97$$

$$= 0.03$$

so let's compute:

$$\frac{P(B | \oplus)}{P(\text{not } B | \oplus)} =$$

$$\left(\frac{0.01}{0.99} \right) \left(\frac{0.98}{0.03} \right)$$

99 to 1
odds
against B

98 to 3 odds
in favor of
B

recall $o = \frac{p}{1-p}$
odds \uparrow probability

$$= \frac{98}{(99)(3)} = \frac{98}{297}$$

(odds in favor of B)

from which

$$p = \frac{o}{1+o} = \frac{\frac{98}{297}}{1 + \frac{98}{297}} = \frac{98}{98+297} = \frac{98}{395} \approx 0.25$$

as before

method 3) Bayes's Theorem in probability form ^③

$$P(B|\oplus) = \frac{P(B) P(\oplus|B)}{P(\oplus)}$$

$0.01 \downarrow$ $0.98 \downarrow$

annoying denominator (normalizing constant) \uparrow $P(\oplus)$ \leftarrow ?
 prediction \leftarrow how compute $P(\oplus)$?

(truth) {B, G} (unknown) \rightarrow data (observable)

(data) { \oplus, \ominus } (Statistical) inference about data

$P(B|\oplus)$
 \uparrow \uparrow
 (truth) (data)
 (unknown) \rightarrow search for truth on basis of data
 (Statistical) inference

\leftrightarrow prediction

$P(\oplus) = ?$ I don't know much at all about \oplus by itself; if I knew B or G, bingo

unknown (true) state of world may well be unobservable

\mathcal{I} (want to predict) (hard)

new creative

(4)

laziness idea:

when \mathcal{I} is hard,

[set help]

(D.V. Lindley)
[extend the conversation]

find some other aspect of world \mathcal{X} upon which \mathcal{I} depends, & predict

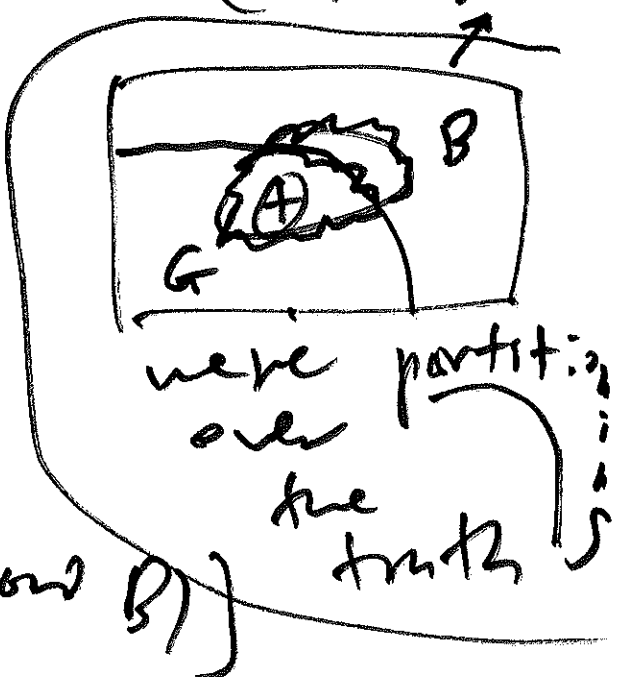
\mathcal{I} in 2 stages: $\left\{ \begin{array}{l} \mathcal{X} \\ (\mathcal{I} | \mathcal{X}) \end{array} \right\}$ indirect

direct

data (\mathcal{I})

other info (\mathcal{X}): $\{G, B\}$

$$\begin{aligned}
 P(\oplus) &= P(\oplus \text{ and } G) + P(\oplus \text{ and } B) \\
 &= P[(\oplus \text{ and } G) \text{ or } (\oplus \text{ and } B)]
 \end{aligned}$$



$$= P(G) P(\oplus | G) + P(B) P(\oplus | B)$$

$$P(\oplus) = \frac{\Sigma \cdot (\Sigma | \Sigma)}{P(G) \cdot P(\oplus | G)} + \frac{\Sigma \cdot (\Sigma | \Sigma)}{P(B) \cdot P(\oplus | B)} \quad (5)$$

$$= (0.99) \left[\underset{\uparrow 0.97}{1 - P(\ominus | G)} \right] (0.01) (0.98)$$

So finally

$$= (0.99)(0.03) + (0.01)(0.98)$$

$$(0.0297) + (0.0098) = 0.0395$$

$$P(B | \oplus) = \frac{P(B) P(\oplus | B)}{P(\oplus)}$$

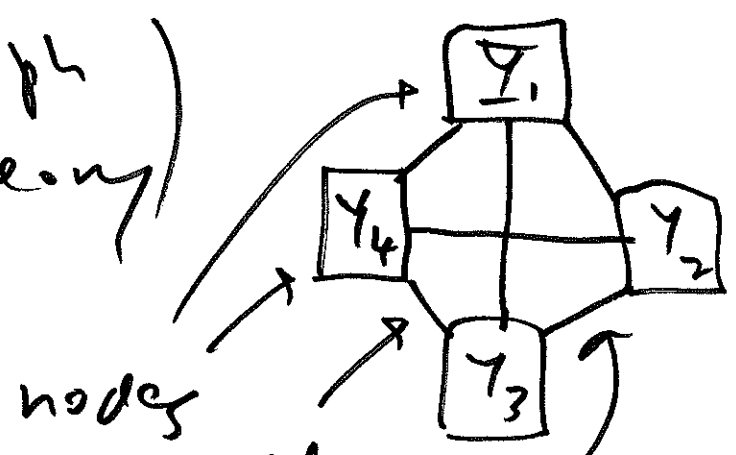
DG ch. 3

$$= \frac{(0.01)(0.98)}{0.0395} = \frac{98}{395} = 0.25$$

Random variables

$P(I = \gamma)$
 \uparrow random variable (process) (potential)
 \uparrow a possible value of I (outcome) (kinetic)

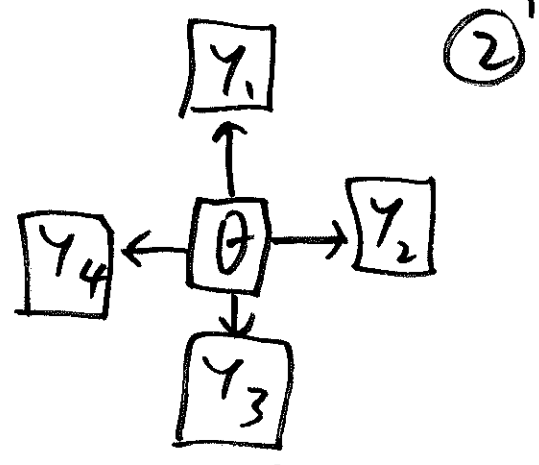
(graph theory)



nodes
edge

Y_i : dependent
4 nodes
6 edges

$x \rightarrow y$
 $x \neq y$
are dependent



$x \rightarrow y$
 x causes
 y
5 nodes
4 edges

n nodes \leftarrow # data points
 $\binom{n}{2}$ edges = $\frac{n(n-1)}{2}$

$(n+1)$ nodes
 n edges = $O(n)$

$= O(n^2)$
this is of order n^2
= Big "oh" of n^2

now
 Y_i are conditionally independent given θ

$O(n^2)$ in this model, the past and the future are conditionally independent given the truth (θ)